

L Number	Hits	Search Text	DB	Time stamp
1	1	"20040046736" and regions	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 12:14
2	0	"20040046736" and sub-regions	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 11:35
3	0	"20040046736" and region\$1 and devide	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 11:35
4	0	"20040046736" and region\$1 and divide\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 11:35
5	0	6,661,918.pn. and sub-regions	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 11:36
6	0	6,125,198.pn. and sub-regions	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 11:37
7	1	6,125,198.pn. and regions and divide\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 12:14
8	0	6,125,198.pn. and depth	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 12:14
9	1	"20040046736" and depth	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 12:15
10	1	"20040046736" and depth and coordinate\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 12:19
11	1	"20040046736" and selected and object and interest	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 13:02
12	1	"20040046736" and selected	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 13:02
-	584	stereo adj vision	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/13 15:42

-	203	stereo adj vision and interface\$6 and application	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:42
-	30	stereo adj vision and interface\$6 and application adj program and run\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:43
-	30	stereo adj vision and interface\$6 and application adj program and run\$9 and computer	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:43
-	26	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:43
-	26	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:26
-	8	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:44
-	8	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:45
-	8	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:45
-	8	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:46
-	8	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:46
-	8	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:47
-	8	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:47

-	8	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:47
-	8	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:48
-	8	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:48
-	0	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 and objetc and interset\$6 AND CONTROL\$6 and region\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:49
-	0	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 and object and interset\$6 AND CONTROL\$6 and region\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:49
-	8	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 and object and interest\$6 AND CONTROL\$6 and region\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 10:23
-	7	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 and object and interest\$6 AND CONTROL\$6 and region\$1 and position\$6 and location and search and point and interest	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:51

-	0	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 and object and interest\$6 AND CONTROL\$6 and region\$1 and position\$6 and location and search and point and interest and close\$6 and map and position and coordinate\$1 and position and indicator	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:52
-	4	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 and object and interest\$6 AND CONTROL\$6 and region\$1 and position\$6 and location and search and point and interest and close\$6 and map and position and coordinate\$1 and position and indicator	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 09:53
-	8	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 and object and interest\$6 AND CONTROL\$6 and region\$1 and position\$6 and location	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 10:15
-	13	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 12:45
-	1	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 and object and interest\$6 AND CONTROL\$6 and region\$1 and sub adj region\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 10:24
-	1	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and sub adj region\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 10:24
-	1	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and sub adj region\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 10:25
-	3	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and divide\$9 adj region\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 10:25
-	2	"20040046736"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 08:17

-	1	"20040046736" and stereo and vision	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 14:43
-	1	"20040046736" and capture\$6 and image	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 15:04
-	1	"20040046736" and processing and image	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 14:59
-	1	"20040046736" and processing and image and user	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 14:59
-	1	"20040046736" and capture\$6 and image and process\$6 and user	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 15:05
-	1	"20040046736" and capture\$6 and image and process\$6 and user and stereo and vision	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 15:49
-	0	"20040046736" and capture\$6 and image and process\$6 and user and stereo and vision and map and coordinate\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 15:50
-	1	"20040046736" and capture\$6 and image and process\$6 and user and stereo and vision and coordinate\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 16:06
-	1	"20040046736" and reference	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 16:06
-	1	"20040046736" and reference and compare\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 10:49
-	0	"20040046736" and compare\$6 with reference	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 16:09
-	0	"20040046736" and compare\$6 and reference adj camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 16:09
-	3	6,720,949	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 16:11
-	3	6,720,949.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/12 16:11

-	0	6,720,949.pn. and reference adj camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/12 16:11
-	1	6,720,949.pn. and two adj cameras	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/12 16:11
-	0	6,720,949.pn. and two adj cameras and compare\$6 adj images	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/12 16:12
-	0	"20040046736" and two adj cameras and compare\$6 adj images	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/12 16:12
-	2	5,917,937.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/12 16:13
-	0	5,917,937.pn. and two adj cameras and compare\$6 adj images	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/12 16:14
-	0	5,917,937.pn. and cameras and compare\$6 adj images	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/12 16:14
-	0	5,917,937.pn. and two adj cameras and compare\$6 and images	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/12 16:14
-	1	5,917,937.pn. and cameras and compare\$6 and images	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/12 16:14
-	2	5,917,937.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/13 07:06
-	1	5,917,937.pn. and compare\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/13 07:06
-	19	stereo adj vision and reference adj camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/13 07:13
-	14	stereo adj vision and reference adj camera and feature\$1 and pair\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/13 15:35
-	1	"20040046736" and reference and compare\$6 and PAIR	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/13 12:09

-	1	"20040046736" and reference and compare\$6 and PAIR and filter	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 12:58
-	4	stereo adj vision and reference adj camera and feature\$1 and pair\$1 and filter	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:32
-	0	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and two adj cameras and compare\$6 adj images	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 12:44
-	0	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and two adj cameras and compare\$6 adj images	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 12:44
-	3	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and reference and compare\$6 and PAIR and filter\$1 and capture\$6 and image and capture\$6 and image and process\$6 and user and stereo and vision and coordinate\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 12:47
-	0	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and rank	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 12:59
-	1	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 13:35
-	0	stereo adj vision and reference adj camera and feature\$1 and pair\$1 and filter and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 13:35
-	1	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 13:36
-	1	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 13:42
-	1	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 14:17
-	1	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 14:32
-	0	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and divide\$9 and block\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 14:21

-	0	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and divide\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 14:22
-	0	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and (divide\$9 or split\$9) and block\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 14:22
-	0	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and (divide\$9 or split\$9 OR DIFFERENTIAIE) and block\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 14:22
-	0	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and (divide\$9 or split\$9 or differentiate) and block\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 14:23
-	1	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:02
-	0	5,159,159.pn	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 14:29
-	1	5,159,159.pn. and horizontal	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 14:29
-	0	5,159,159.pn. and horizontal and synch	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 14:29
-	0	5,159,159.pn. and horizontal and synch\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 14:29
-	1	5,159,159.pn. and horizontal	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 14:29
-	0	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and pattern and luminance and pixels	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:02
-	0	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and luminance and pixels	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:02
-	0	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and luminance and pixel\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:03

-	1	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and pixel\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:03
-	0	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and pixel\$1 and (luminance or birgtness)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:03
-	1	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and pixel\$1 and pattern	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:03
-	1	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and pixel\$1 and pattern and contrast	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 12:31
-	0	"20040046736" and block adj pixel\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:29
-	1	"20040046736" and pixel\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:40
-	3	stereo adj vision and reference adj camera and feature\$1 and pair\$1 and filter and pixel\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:38
-	8	stereo adj vision and refereñce adj camera and feature\$1 and pair\$1 and matrix and pixel\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:37
-	0	stereo adj vision and reference adj camera and feature\$1 and pair\$1 and matrix and pixel\$1 and "8x8"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:38
-	0	stereo adj vision and matrix and pixel\$1 and "8x8"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:38
-	12	stereo adj vision and reference adj camera and matrix and pixel\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:39
-	1	"20040046736" and matrix	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:40
-	241	stereo adj vision and display and pixel\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:42

-	4	stereo adj vision and display and pixel\$1 and active adj matrix	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:45
-	0	stereo adj vision and display and pixel\$1 and active adj matrix and "8x8"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:45
-	9	stereo adj vision and display and pixel\$1 adj block	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/13 15:46
-	1	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and pixel\$1 and pattern and contrast and compare	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:05
-	0	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and pixel\$1 and pattern and contrast and compare and cluster\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 12:33
-	2	6,125,198.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 11:36
-	2	6,661,918.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 12:54
-	1	6,661,918.pn. and cluster\$1 and image\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 12:56
-	1	6,661,918.pn. and cluster\$1 and image\$1 and compare and position	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:04
-	0	6,661,918.pn. and cluster\$1 and image\$1 and compare and position and coordinate\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:04
-	1	6,661,918.pn. and cluster\$1 and image\$1 and compare and position	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 11:36
-	1	"20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and pixel\$1 and pattern and contrast and compare and features	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:32

-	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature\$1 and pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1 and image\$1 and reference and camera\$1 and compare\$8 and create\$9 and image\$1 and cluster\$1 and threshold	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:13
-	1	6,661,918.pn. and cluster\$1 and image\$1 and compare and position and threshold	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:13
-	1	6,661,918.pn. and cluster\$1 and image\$1 and compare and position and threshold and eliminate	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 14:16
-	1	"20040046736" and head\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:43
-	1	"20040046736" and head\$1 and smooth\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:38
-	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature\$1 and pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1 and image\$1 and reference and camera\$1 and compare\$8 and create\$9 and image\$1 and cluster\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:38
-	1	"20040046736" and head\$1 and smooth\$6 and image and frames	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:41
-	1	"20040046736" and head\$1 and smooth\$6 and frames	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:41
-	0	"20040046736" and hand\$1 and orient\$6 and calculat\$6 and informat\$6 and object\$1 and posit\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:45
-	1	"20040046736" and hand\$1 and orient\$6 and calculat\$6 and informat\$6 and object\$1 and posit\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:49
-	1	"20040046736" and hand\$1 and orient\$6 and calculat\$6 and informat\$6 and object\$1 and posit\$6 and coordinate\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:15
-	2	"20040046736" and computer	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 14:16
-	1	"20040046736" and computer and interface	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 14:23

-	1	"20040046736" and capture\$6 and image\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 11:32
-	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature\$1 and pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1 and image\$1 and reference and camera\$1 and compare\$8 and create\$9 and image\$1 and cluster\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 13:46
-	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature\$1 and pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1 and image\$1 and reference and camera\$1 and compare\$8 and create\$9 and image\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 14:17
-	7	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 and object and interest\$6 AND CONTROL\$6 and region\$1 and position\$6 and location and search and point and interest and close\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 13:50
-	1	6,661,918.pn. and map\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:33
-	0	6,125,198.pn. and map\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 14:18
-	0	"20040046736" and map\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 14:17
-	0	"20040046736" and mapp\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 14:18
-	0	"20040046736" and map	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 14:18
-	0	6,125,198.pn. and map	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:26
-	1	"20040046736" and stereo adj image and stereo adj camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 14:58
-	0	"20040046736" and x-axis	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 14:58

-	1	"20040046736" and x and axis	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 15:00
-	1	"20040046736" and x and axis and hand\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 15:33
-	1	"20040046736" and X and axis and Z	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 15:34
-	1	"20040046736" and X and axis and Z and depth	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 15:35
-	1	"20040046736" and (storage or stor\$6) and orient\$6 and posit\$6 and coordinate\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 16:25
-	0	"20040046736" and avatar	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 16:29
-	0	6,125,198.pn. and avatar	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 16:26
-	0	6,661,918.pn. and avatar	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 16:33
-	2	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and avatar	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 16:27
-	2	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and avatar	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 16:28
-	1	stereo adj vision and indicator\$1 and avatar	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 16:28
-	8	stereo adj vision and avatar	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 16:36
-	1	"20040046736" and animation	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 16:30
-	0	"20040046736" and animation and facial and sens\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 16:30

-	1	"2004046736" and animation and face and sens\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:30
-	0	6,661,918.pn. and animation	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:33
-	0	6,661,918.pn. and animation	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:33
-	8	stereo adj vision and avatar and indicat\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:38
-	2	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:39
-	7	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:39
-	2	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and application adj program and run\$9 and computer	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:39
-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:43
-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:41
-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and user and select\$6 AND CONTROL\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:41
-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:42

-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and view\$1 and user and select\$6 AND CONTROL\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:42
-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and user and select\$6 AND CONTROL\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:42
-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and user and select\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:42
-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and user and select\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:42
-	7	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and image\$1 and detect\$9 and object\$1 and user and select\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:43
-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:43
-	7	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:43
-	7	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:44
-	4	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:45
-	7	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:45
-	7	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:45

-	6	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 06:47
-	6	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 08:57
-	2	"20010033675"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 07:43
-	1	"20010033675" and map	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 10:10
-	6	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and map\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 07:44
-	2	"20040046736" and mouse	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 08:17
-	1	"20010033675" and virtual	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 08:48
-	0	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and neutral and position and corresponding and hand and object and selected and velocity and function and applied and avatar and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:00

-	1	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and neutral and hand and object and selected and velocity and function and applied and avatar and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:01
-	1	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and neutral and hand and object and selected and velocity and avatar and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:01
-	1	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and hand and object and selected and velocity and avatar and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:01
-	1	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and selected and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:02
-	1	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and selected and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:02

-	1	stereo adj vision and avatar and stereo adj vision and interface\$6 and computer and camera\$1 and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and selected and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:02
-	1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and selected and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:03
-	1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and detect\$9 and object\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and selected and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:03
-	1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and object\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and selected and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:03
-	1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and object\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:03
-	1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and object\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:03
-	1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and object\$1 and user and select\$6 and coordinate\$1 and virtual and hands and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:04
-	1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and object\$1 and user and virtual and hands and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:05

-	1	stereo adj vision and avatar and computer and camera\$1 and image\$1 and object\$1 and user and virtual and hands and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:05
-	1	stereo adj vision and avatar and object\$1 and user and virtual and hands and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:05
-	1	stereo adj vision and avatar and virtual and hands and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:05
-	1	stereo adj vision and avatar and virtual and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:05
-	1	stereo adj vision and avatar and virtual and velocity and roam and virtual and environment	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:06
-	1	stereo adj vision and avatar and virtual and velocity and roam and environment	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:06
-	4	avatar and virtual and velocity and roam and environment	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:19
-	3	avatar and virtual and velocity and roam and environment and hand	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:20
-	1	avatar and virtual and velocity and roam and environment and hand\$1 and stereo adj vision	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:20
-	2	avatar and virtual and velocity and roam and environment and hand\$1 and interface\$6 and computer and camera\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:21
-	2	avatar and virtual and velocity and roam and environment and hand\$1 and computer and camera\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:21
-	3	avatar and virtual and velocity and roam and environment and hand\$1 and computer	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:21

-	1	avatar and virtual and velocity and roam and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and neutral and hand and object and selected and velocity and function and applied and avatar and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:23
-	1	avatar and virtual and velocity and roam and environment and hand\$1 and computer and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and neutral and hand and object and selected and velocity and function and applied and avatar and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:22
-	1	avatar and virtual and velocity and roam and environment and hand\$1 and computer and view\$1 and user and virtual and hands and avatar and neutral and hand and object and selected and velocity and function and applied and avatar and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:22
-	1	avatar and virtual and velocity and roam and environment and hand\$1 and computer and user and virtual and hands and avatar and neutral and hand and object and selected and velocity and function and applied and avatar and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:22
-	1	avatar and virtual and velocity and roam and environment and hand\$1 and computer and user and virtual and hands and avatar and neutral and hand and velocity and function and applied and avatar and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:23
-	1	avatar and virtual and velocity and roam and environment and hand\$1 and computer and user and virtual and hands and avatar and neutral and hand and velocity and function and applied and avatar and roam and virtual and environment	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:23
-	1	avatar and virtual and velocity and roam and environment and hand\$1 and computer and user and virtual and hands and avatar and neutral and hand and velocity and function and avatar and roam and virtual and environment	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:23
-	1	avatar and virtual and velocity and roam and environment and hand\$1 and computer and user and virtual and hands and avatar and neutral and hand and velocity and avatar and roam and virtual and environment	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:23

-	3	avatar and virtual and velocity and room and environment and hand\$1 and computer and user and virtual and hands and avatar and hand and velocity and avatar and room and virtual and environment	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:23
-	2	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and velocity and function and applied and avatar and room and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:25
-	2	avatar and virtual and velocity and room and environment and hand\$1 and computer and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and velocity and function and applied and avatar and room and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:24
-	2	avatar and virtual and velocity and room and environment and hand\$1 and computer and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and velocity and function and applied and avatar and room and virtual and environment	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:24
-	2	avatar and virtual and velocity and room and environment and hand\$1 and computer and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and velocity and function and applied and avatar and room and virtual and environment	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:25
-	2	avatar and virtual and velocity and room and environment and hand\$1 and computer and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and velocity and function and applied	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:25
-	3	avatar and virtual and velocity and room and environment and hand\$1 and computer and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and velocity	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:25

-	3	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:26
-	3	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:26
-	3	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:27
-	2	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and camera\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:27
-	0	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and setreo	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:27
-	1	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and stereo	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:28
-	1	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and neutral and object and selected and function and applied and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:29

-	2	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and object and selected and function and applied and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:30
-	2	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and object and selected and function and applied	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:30
-	2	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and object and selected and function	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:30
-	2	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and object and function	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:30
-	2	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and object\$1 and function\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:31
-	3	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and object\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:31

-	2	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and object\$1 and applied	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:31
-	3	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and object\$1 and apply\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:34
-	0	avatar and virtual and velocity and room and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and (un adj selected) and program and application and interface and object\$1 and apply\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:35
-	2	6088035.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:45
-	1	6088035.pn. and selected	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:51
-	1	6088035.pn. and hand\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:51
-	1	"20010033675" and hands	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 10:11

L Number	Hits	Search Text	DB	Time stamp
1	2	6,125,198.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:44
2	49	6,125,198.pn. threshold and calculating and match and feature and pairs and score and disparity and selecting and highest	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:46
3	0	6,125,198.pn. and threshold and calculating and match and feature and pairs and score and disparity and selecting and highest	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:46
4	2	6,125,198.pn. and threshold	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:46
5	0	6,125,198.pn. and threshold and calculating	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:46
6	1	6,125,198.pn. and threshold and calculat\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:47
7	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:47
8	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and score\$9 and disparity	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:48
9	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and selecting and highest	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:48
10	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:48
11	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and score\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:48
12	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and score\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:49
13	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and score\$6 and achieve\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:49

14	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and (score\$6 or acieve\$9)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:49
15	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and (score\$6 or achieve\$9)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:49
16	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:56
17	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and pixel\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:56
18	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:56
19	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 09:59
20	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1 and scene	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 10:00
21	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1 and scene\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 10:00
22	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1 and image\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 10:01
23	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1 and image\$1 and reference adj camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 10:02
24	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1 and image\$1 and reference and camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 10:03
25	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1 and image\$1 and reference and camera and compare\$8	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 10:03
26	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1 and image\$1 and reference and camera and compare\$8 and create\$9 and pairs and image	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 10:04